


The background of the slide features a dark blue, high-tech aesthetic. In the center, a white car is positioned on a blue mechanical test rig. Above the car, a large screen displays a virtual simulation of a road with other vehicles. The scene is surrounded by abstract digital elements, including glowing blue lines and nodes that resemble a network or circuit board, particularly prominent in the top left and bottom right corners.

Virtual Development and Validation Environment for ADAS and RDE

Connect simulation and test

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How to run 100.000.000
(one hundred million😊)
test kilometers per week?

Integrated & Open Development Platform

Connect simulation & test

 TESTBEDS

PROCESSES

 MODELS

...

 DATA

Connect existing elements within
the vehicle development process...



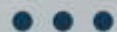
Model.CONNECT™



Testbed.CONNECT™



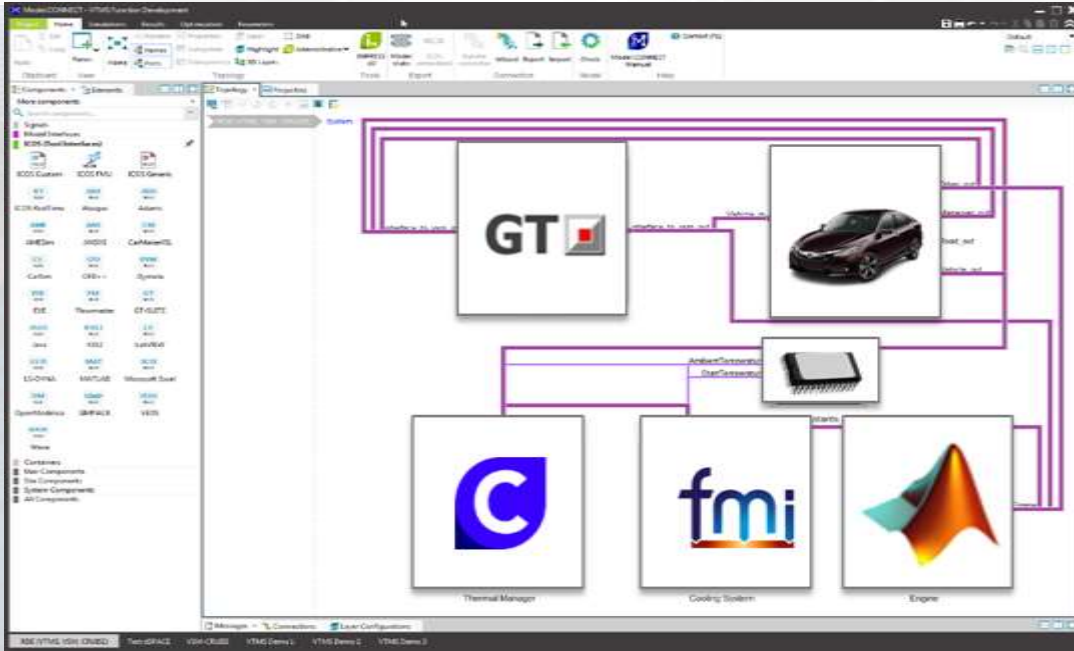
Data.CONNECT



... for early, fast and sound decisions.



Model.CONNECT™



- Neutral, Open, Tool-Free
- Coupling Error Compensation
- Local and Distributed Co-Simulation
- Connecting RT and non-RT Systems



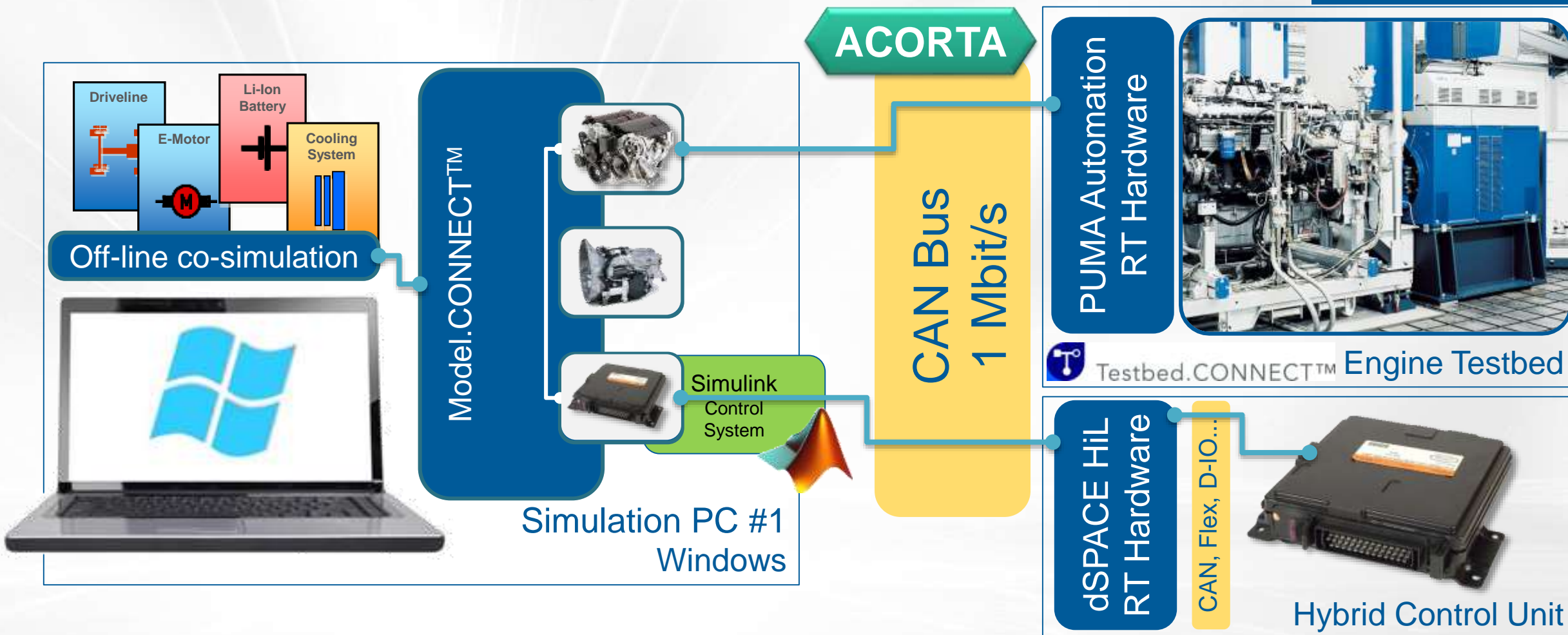
Neutral and open model integration and co-simulation platform, opening the door from simulation to testbed.



Tools specific interfaces (25+ software vendors) and interface standards (FMI)



Model.CONNECT™



REAL-TIME: Connecting RT and non-RT Systems

ACORTA - Synchronizing off-line co-simulation with hardware components



Testbed.CONNECT™

ADAS ENGINEERING SERVICES AT A GLANCE



Functional integration & calibration services
incl. controls & function development for add-on features



Methods & tools
for simulation, testing & validation from lab to road



New predictive/adaptive functions
improving vehicle attributes e.g. fuel efficiency

For new levels of vehicle comfort, safety and efficiency

TRANSFER REAL WORLD SCENARIOS INTO SIMULATED WORLD



REQUIREMENTS ON MODELS:

- Fast, accurate and extendable
- Real-time capability for control function development
- Integration with vehicle dynamics and traffic simulation
- Virtual driving quality assessment
- Execution in a distributed cluster/cloud environment
- Integration environment for HiL and testing applications

IT IS NOT SO IMPORTANT HOW WELL
THE TOOLS WORK FOR THEMSELVES,

**IT IS IMPORTANT HOW WELL
THE TOOLS WORK TOGETHER!**

DEVELOPMENT, TESTING AND VALIDATION OF ACTIVE AND PREVENTIVE SYSTEMS



Model.CONNECT™

Components

FMI
Matlab
AMESim
CRUISE
ADAMS
SIMPACT
LS-Dyna



Test bed

V-ECUs

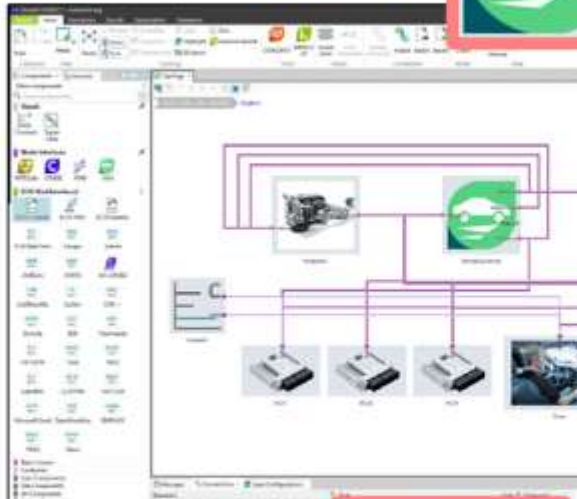


Matlab
VEOS
EVE*



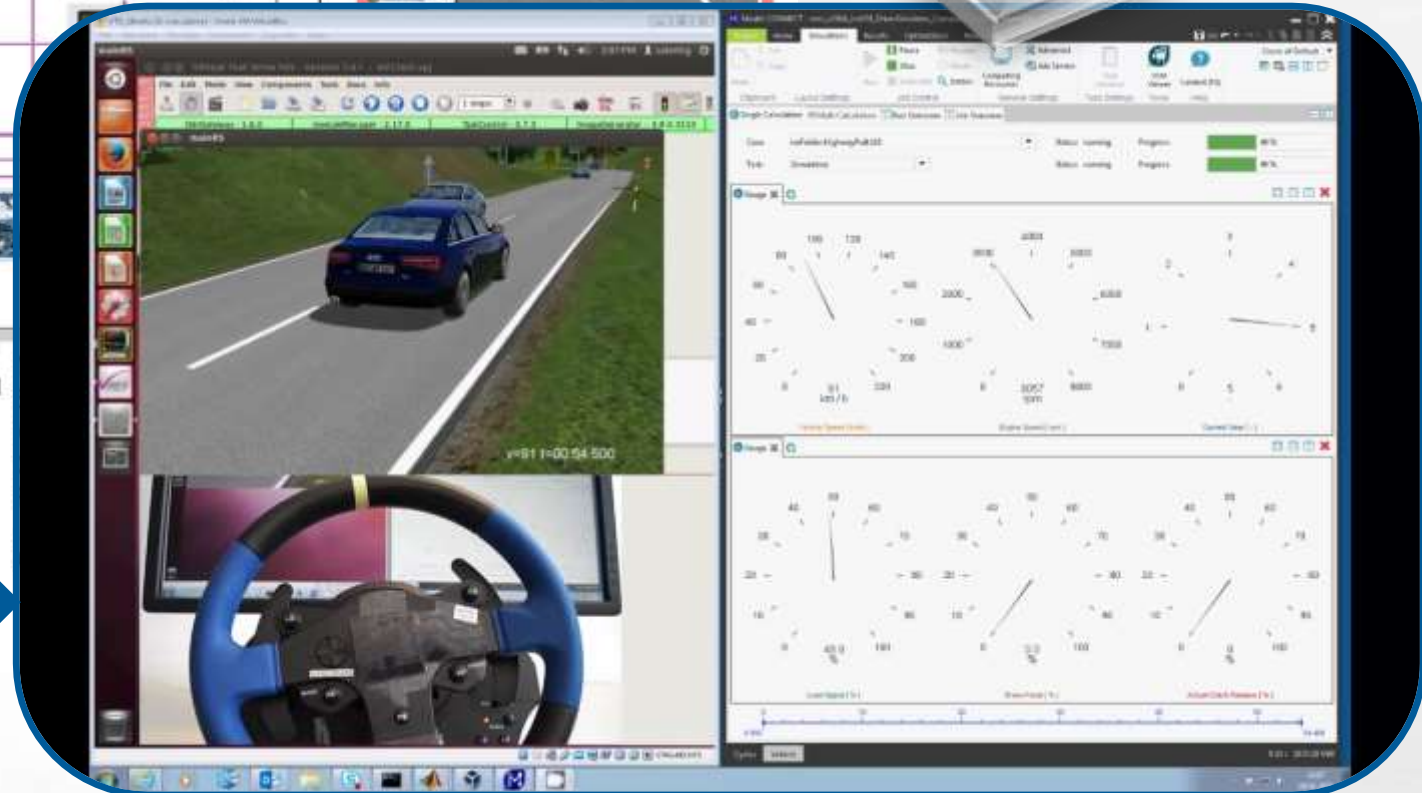
VSM
CarMaker
CarSim
...
Custom

Scenario

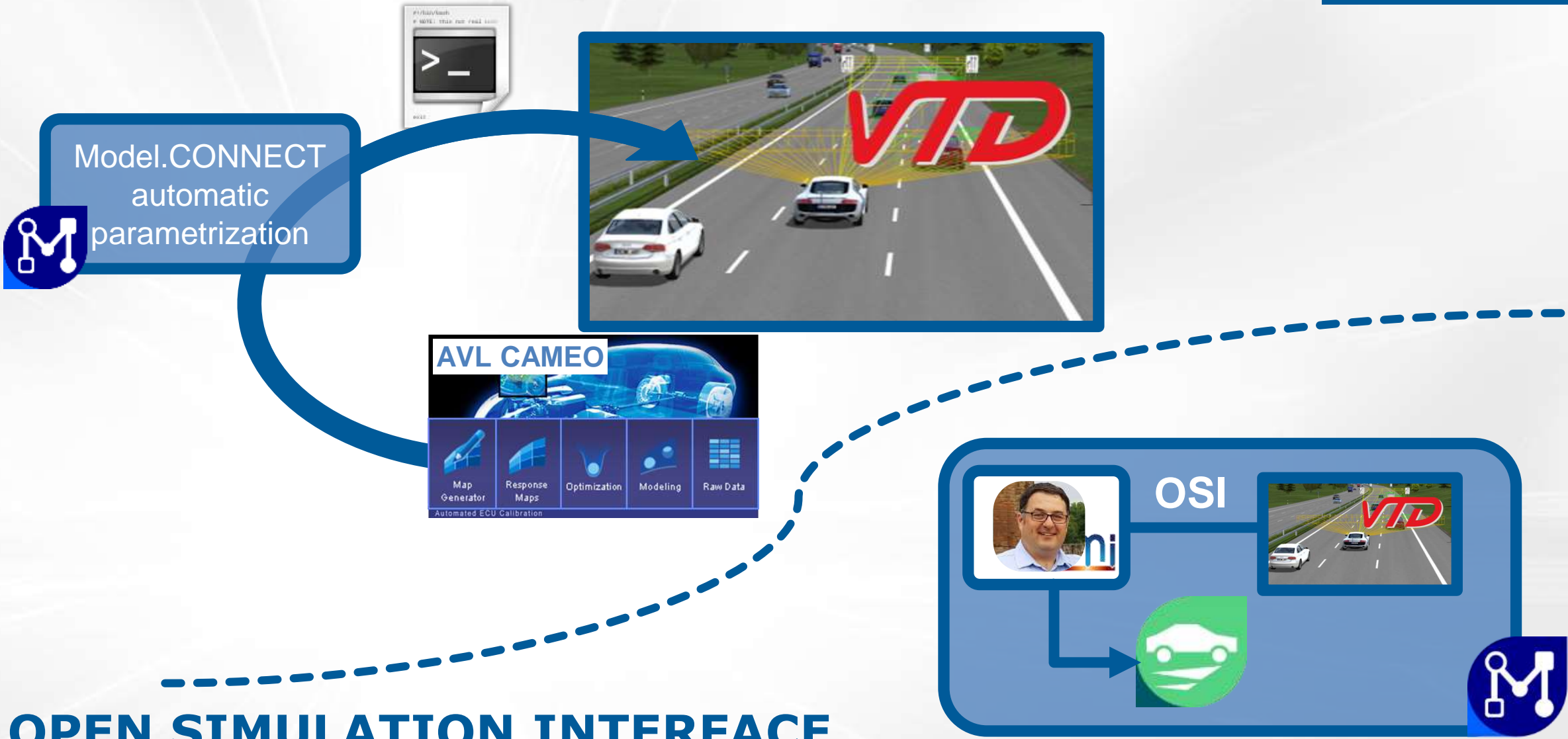


Driver

USE CASE: lane keeping assistant with PlayStation2 steering wheel



VTD VIRES AUTOMATIC PARAMETRIZATION



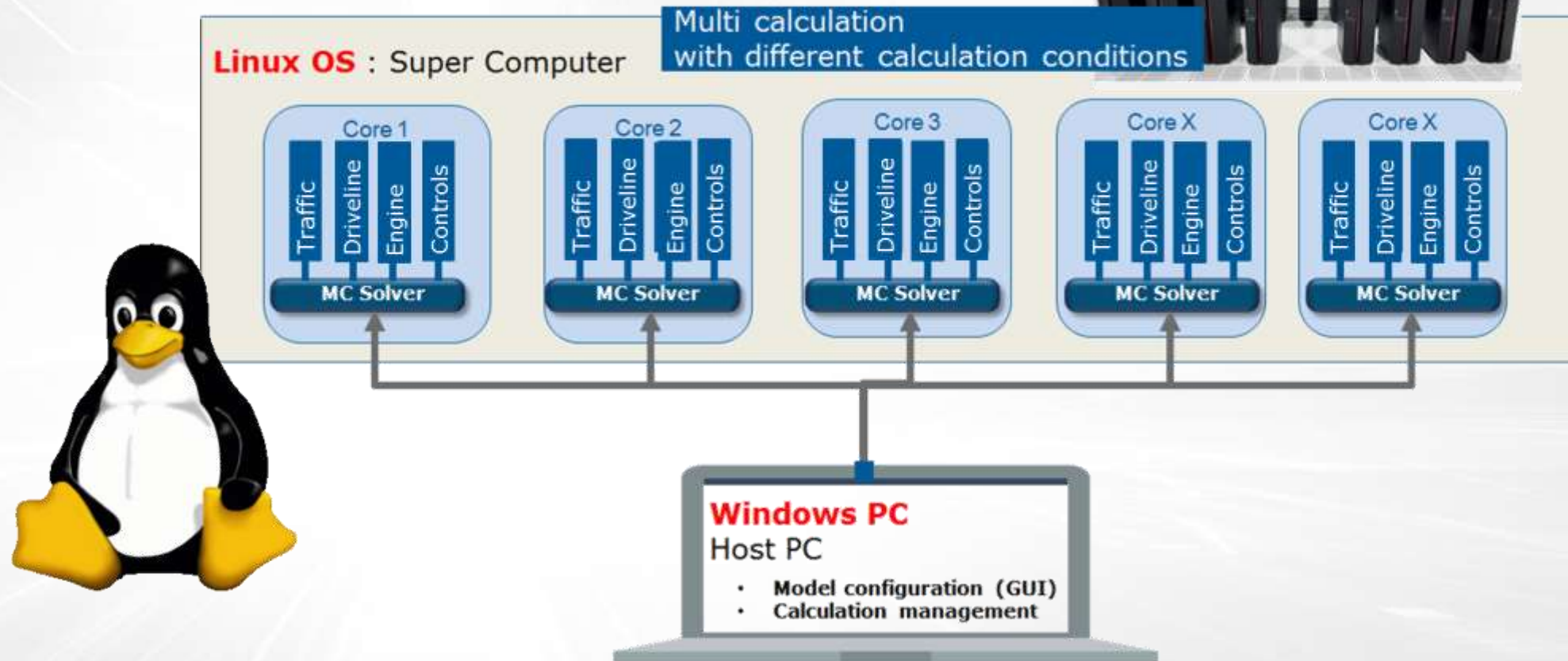
OPEN SIMULATION INTERFACE

LARGE SCALE VALIDATION AND OPTIMIZATION

Model.CONNECT @ LINUX

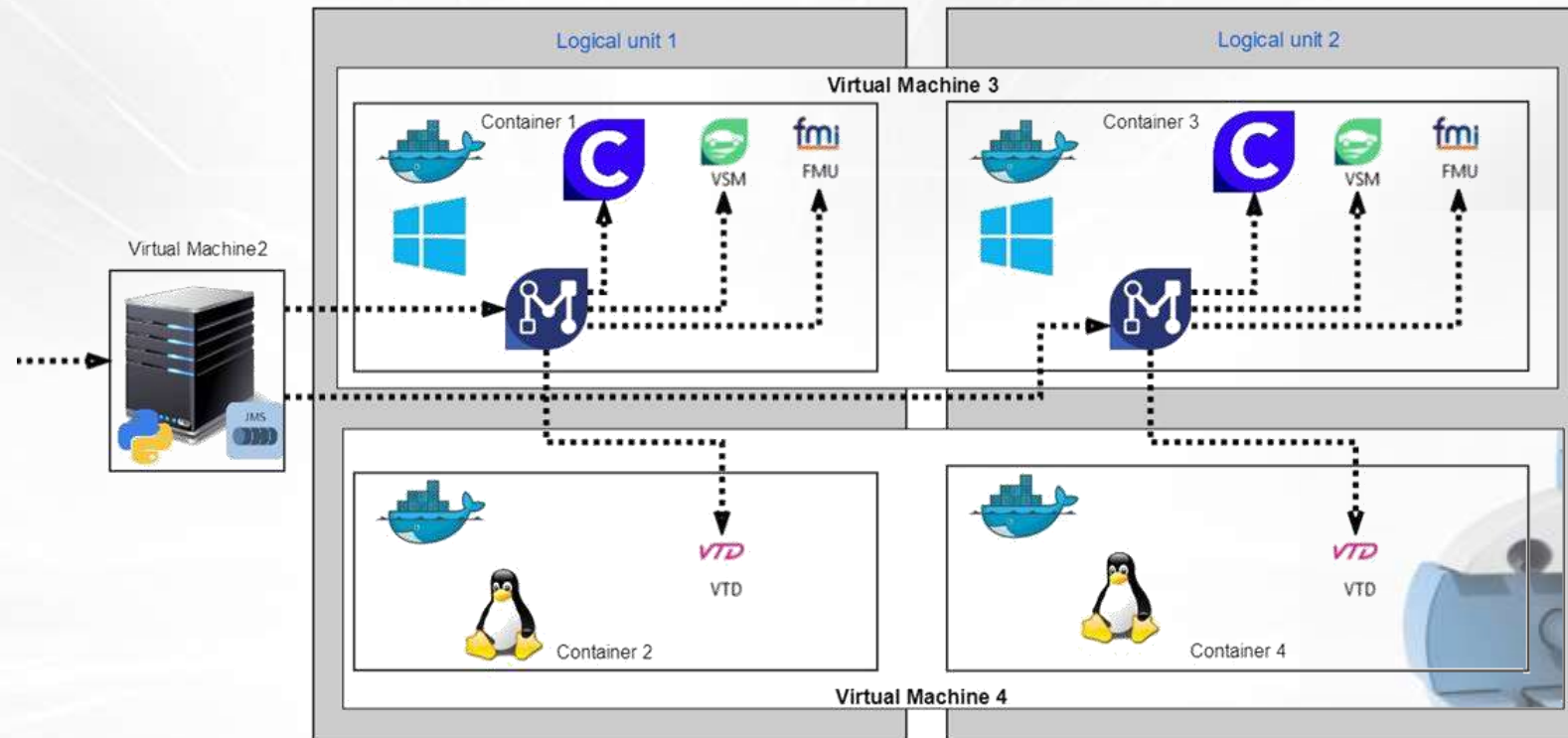


USE CASE: ADAS DRIVING CASE STUDIES WITH OPTIMIZATION TOOL



Model.CONNECT Docker Containers Demonstrator in the Azure Cloud

Use case: ALP.Lab



ADVANCED OPEN VALIDATION ENVIRONMENT



Validation Simulation Environment

Environment
Simulation



Model, SW, Testing
Integration Platform



Tool Environment

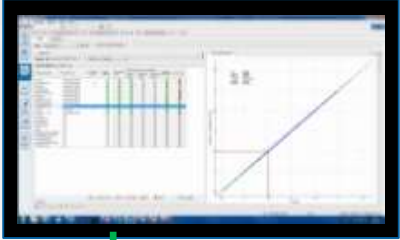
Online & Post-
Processing



Tool Extension
Image Processing



Model Based
Validation



Model.CONNECT™



Signals (closed loop, information)
Object lists
Streams (videos, 3D data,...)

MIL in cloud



Development
Environments

MIL



Inverter



ADAS ECU



HIL



(Mini-)DrivingCube

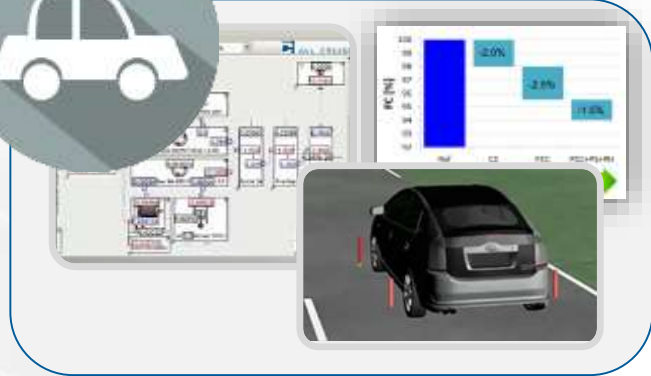


Driving Simulator



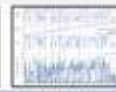
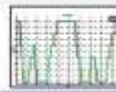
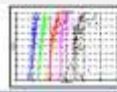
Data Management
Measurement / Parameter

LET'S START A RIDE OF 100.000.000 KM



IETT Annual
Fuel Cost
220.000.000

Example of
Saving Potential:
2%
4.400.000 €



Measurement Calibration Validation



PCC active events	Fuel reduction in %
Only Coasting	2.14
Only Hill cresting	5.00
Only Dip crossing	2.20
Coasting and Hill cresting	5.90
Coasting and Dip crossing	4.33
Hill cresting and Dip crossing	6.56

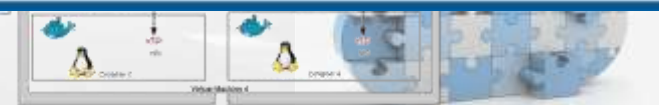
Simulation engine for fuel economy, emission and performance aspects of ADAS function development (ACC/PCC, acceleration, VTMS, drivability etc.)



Preferred integration platform for ADAS functions development and validation.

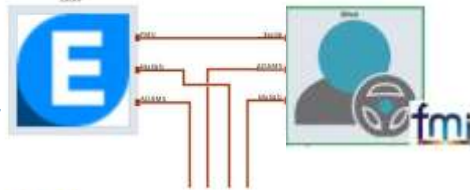
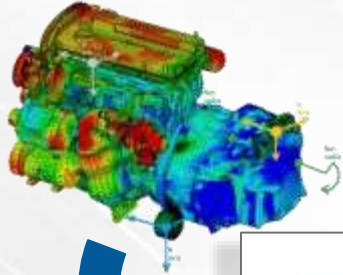


parametrization

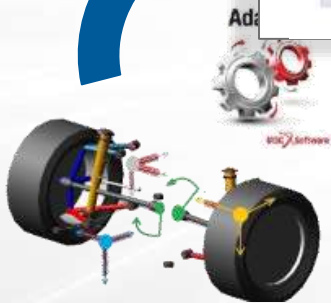
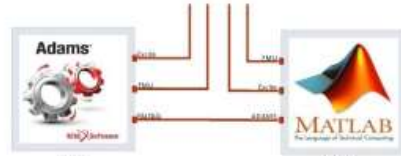


HOLISTIC APPROACH IN NVH ANALYSIS

AVL EXCITE™

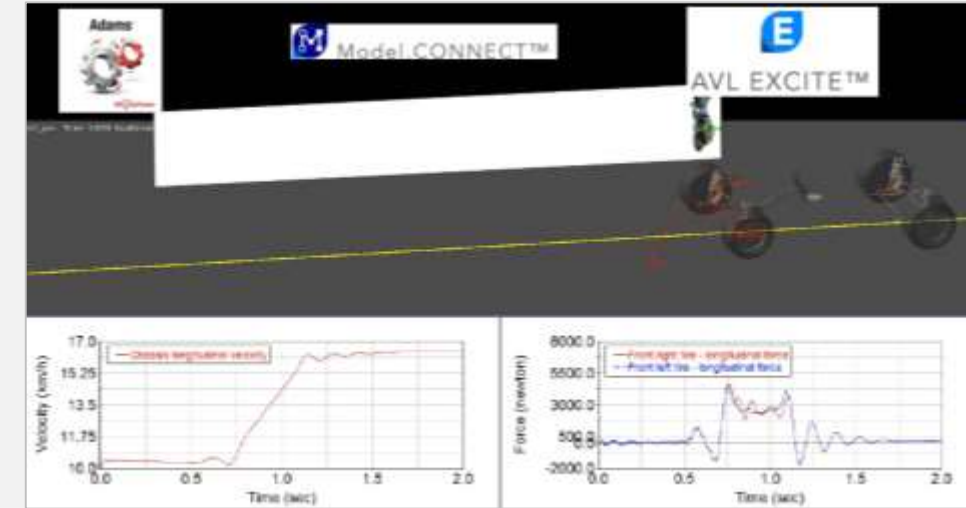


Model.CONNECT™



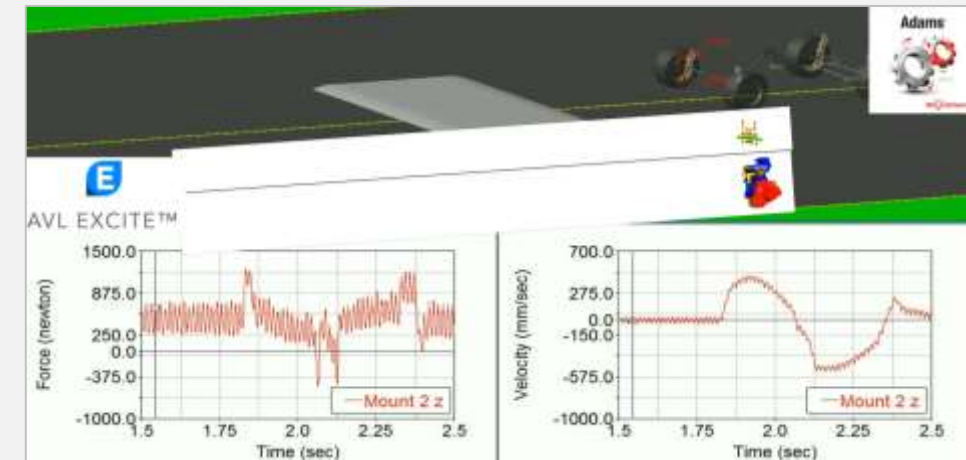
Tip-In-Back-Out:

Clunk and shuffle noise prediction in the driveline.

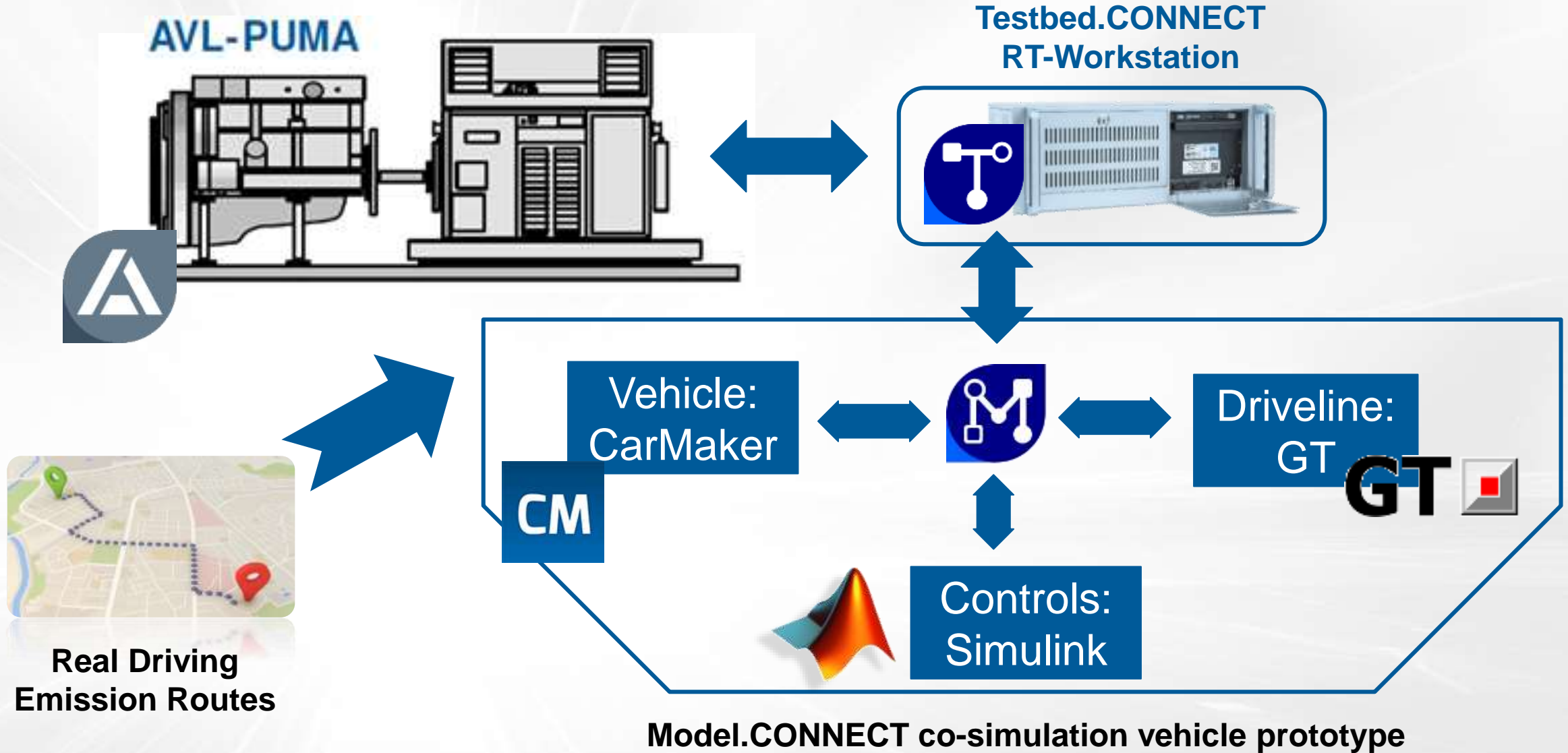


Road Bumper:

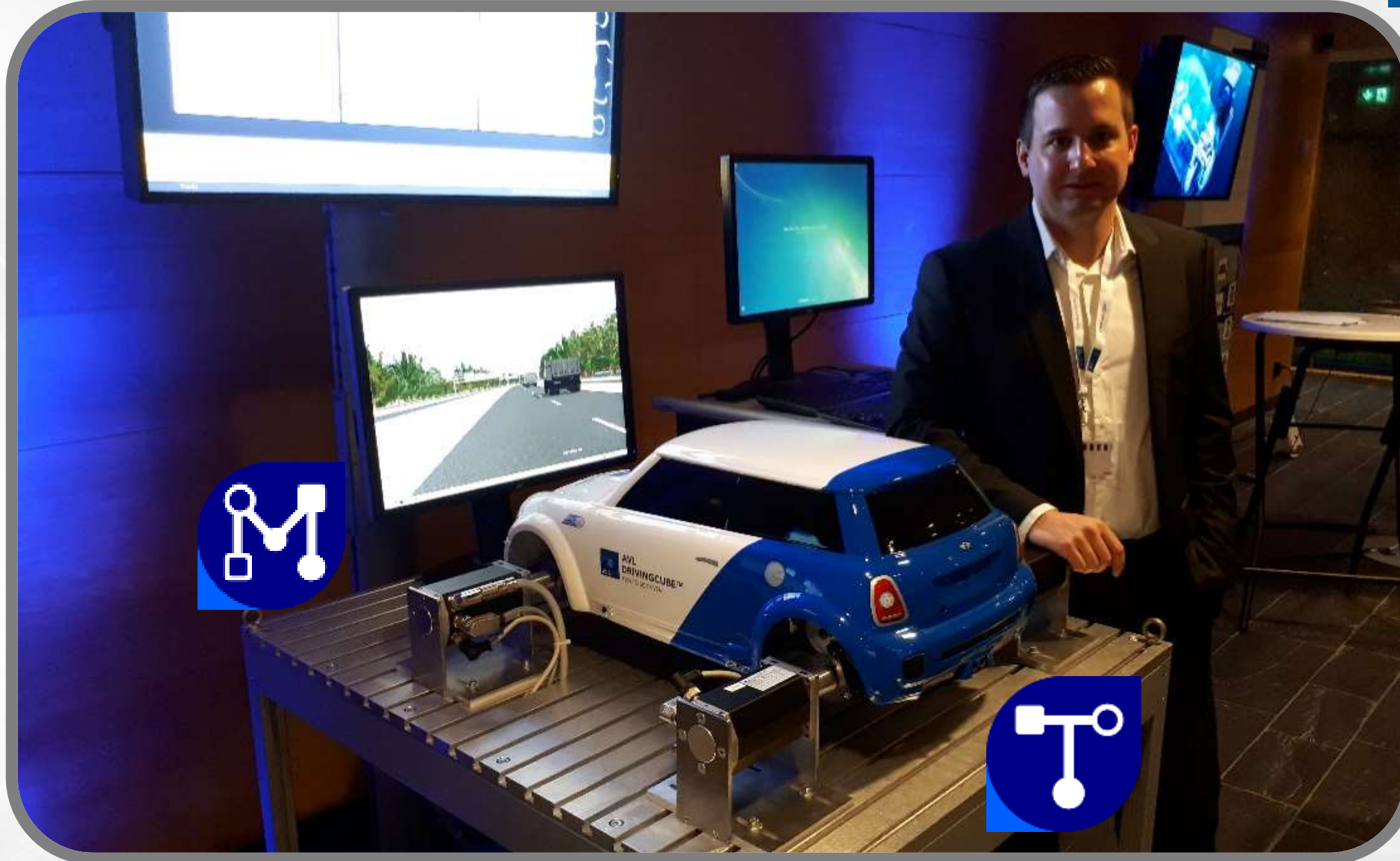
NVH impact on the engine mounts, tires and suspension.



REAL DRIVING EMISSION TESTING ON THE ENGINE TESTBED



AVL Mini-DrivingCube DEMONSTRATOR AT PDiM 2017 IN GOTHENBURG



SIMULATION



TESTING

