



MegaWatt Charging

A Critical Success Factor for Commercial Vehicle Electrification

Anne-Marie Schuppan

Today's Presenter



Anne-Marie Schuppan

- 2010 – 2016 Diplom Mechatronics with specialization to electric drive and control @ TU Dresden
- 2016 – 2022 Expert Software and Functions Engineer for Electric Drive Control @ AVL SFR
- 2022 – today Team Lead Charging @ AVL SFR

Today's Agenda

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About Us

2

Introduction to MegaWatt Charging

3

Standardization

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**MCS System Architecture,
Power Electronics & Control**

5

**Energy Flow and Losses from
Grid to Vehicle**

6

Status NEFTON MCS Project

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Outlook



MegaWatt Charging – A Critical Success Factor for Commercial Vehicle Electrification

About Us



Reimagining Motion

“We are driven by a **passion** to examine the science, mechanics and philosophy of movement. To help create a world that is climate-neutral and one that makes **safe, comfortable, green mobility** a reality for everyone.”

Helmut O. List

Chairman and CEO
AVL List GmbH

AVL at a Glance



1948

Founded



26

Countries
Represented



12,200

Employees Worldwide



10 %

Of Turnover Invested
in Inhouse R&D

75+

Years of Experience

45

Global Tech and
Engineering Centers

68 %

Engineers and
Scientists

2,200

Granted Patents
in Force

Redrawing the Lines of Electrification



E-Mobility

We are relentlessly striving towards climate-neutral mobility. Not just by increasing the efficiency of multiple propulsion systems, but also by pioneering energy from green resources.



20+

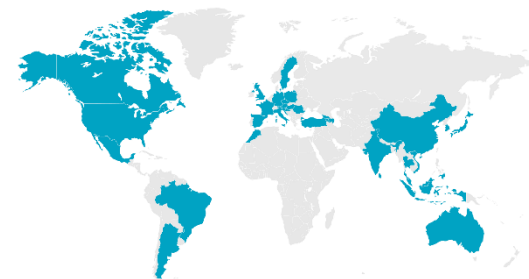
Years of
Experience

5,700+

E-Mobility
Experts

900+

Executed
Battery
Projects



15+

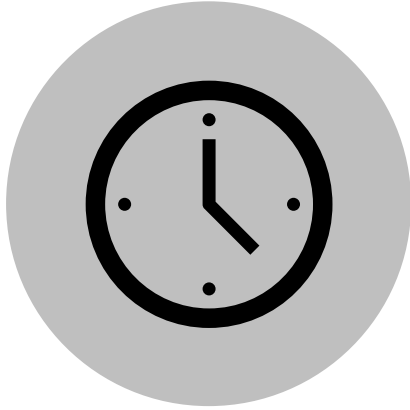
Locations for
Battery
Development

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Introduction to MegaWatt Charging

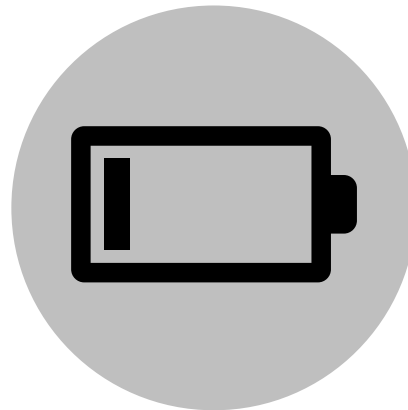
Charging Infrastructure for BEV HD Vehicles

Motivation



Allowed non-stop
driving time (EU)

4,5 h driving
45 min break
4,5 h driving



Consumption

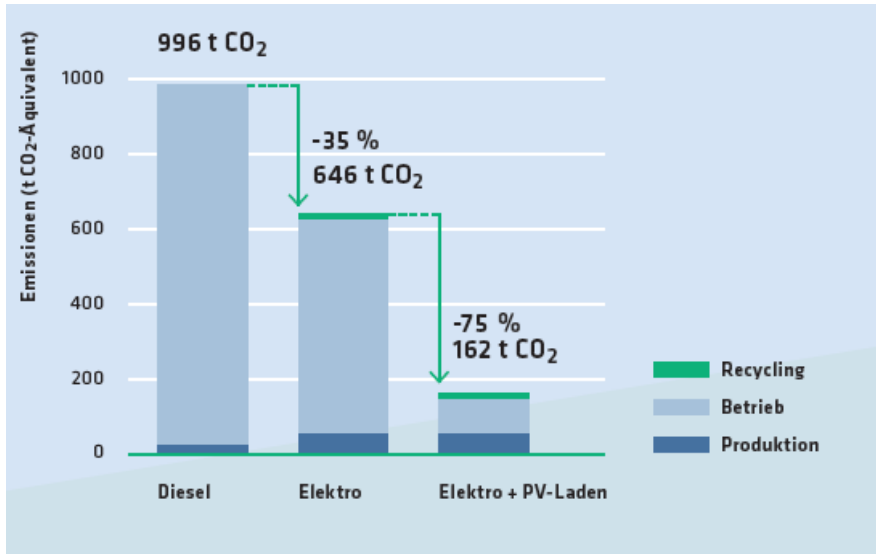
110–200 kWh / 100 km
400–800 km / day
360–800 kWh Battery



Charging Power

> 1000 kW
(during break stop)

Legislation / Emissions / Decarbonization



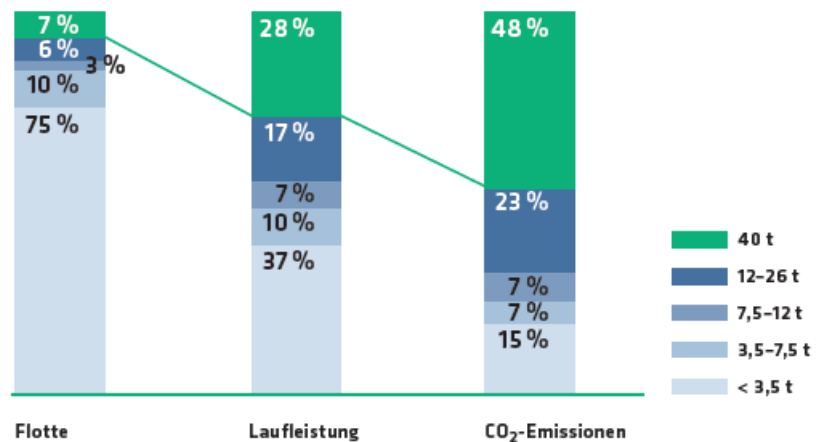
Legislation

- Reduction of emissions per kilometer by 8.5 % since 1995
- EU-Target: Reduction of 45 % until 2030

Emissions over product lifecycle

- Majority of emissions are generated during operation
- Majority of emissions are generated by 40 t truck fleet

Flottenzusammensetzung



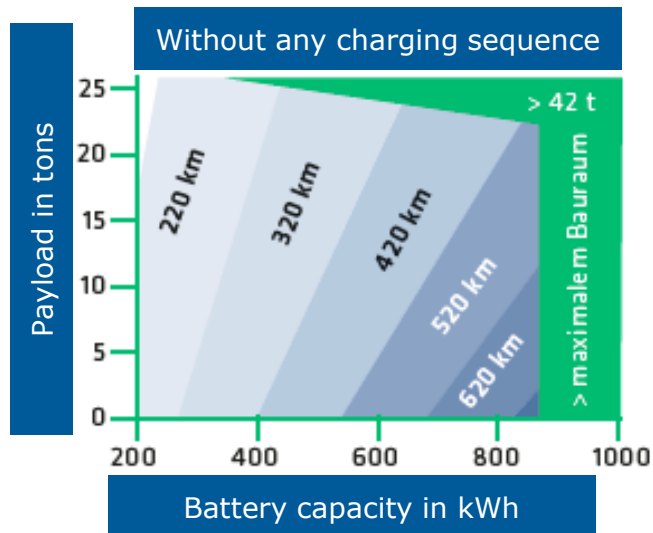
The biggest lever in decarbonization is therefore the driving technology

Today's presentation focuses on battery electric trucks only

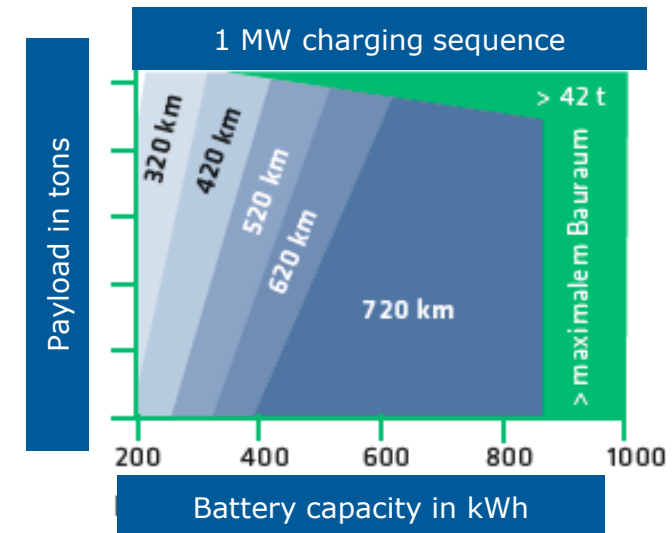
Electrification of Freight Transport Challenges

Influence of battery capacity / payload on range

Targeted Range: 720 km @ 9 hours driving time



Result: > 800 kWh battery pack, no payload



Result: 600 kWh battery pack, full payload

MegaWatt charging infrastructure on a large scale is mandatory

Electrification of Freight Transport Challenges

Influence of charging power / installed infrastructure on the time loss per 9 h driving time

Starting Conditions

100 % SOC
700 km driving distance
> 750 kW Charger every 50 km

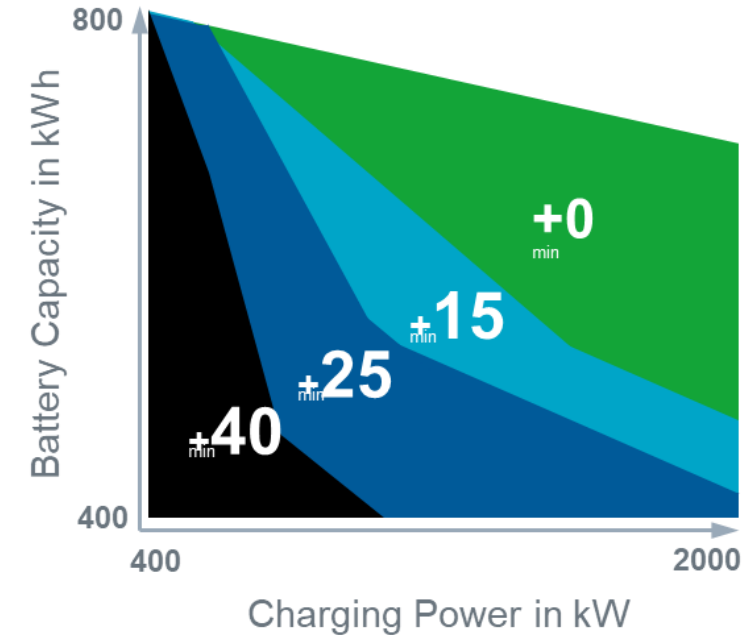
State of the Art

400 kWh battery capacity
400 kW charging Power  7,4 % time loss

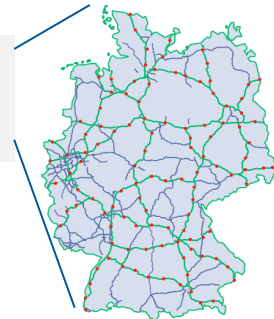
Future

600 kWh battery capacity
1500 kW charging power  **No time loss**

MegaWatt charging technology for trucks is mandatory
MegaWatt charging infrastructure on a large scale is mandatory



Every 50 km
one chargepoint
with > 750 kW

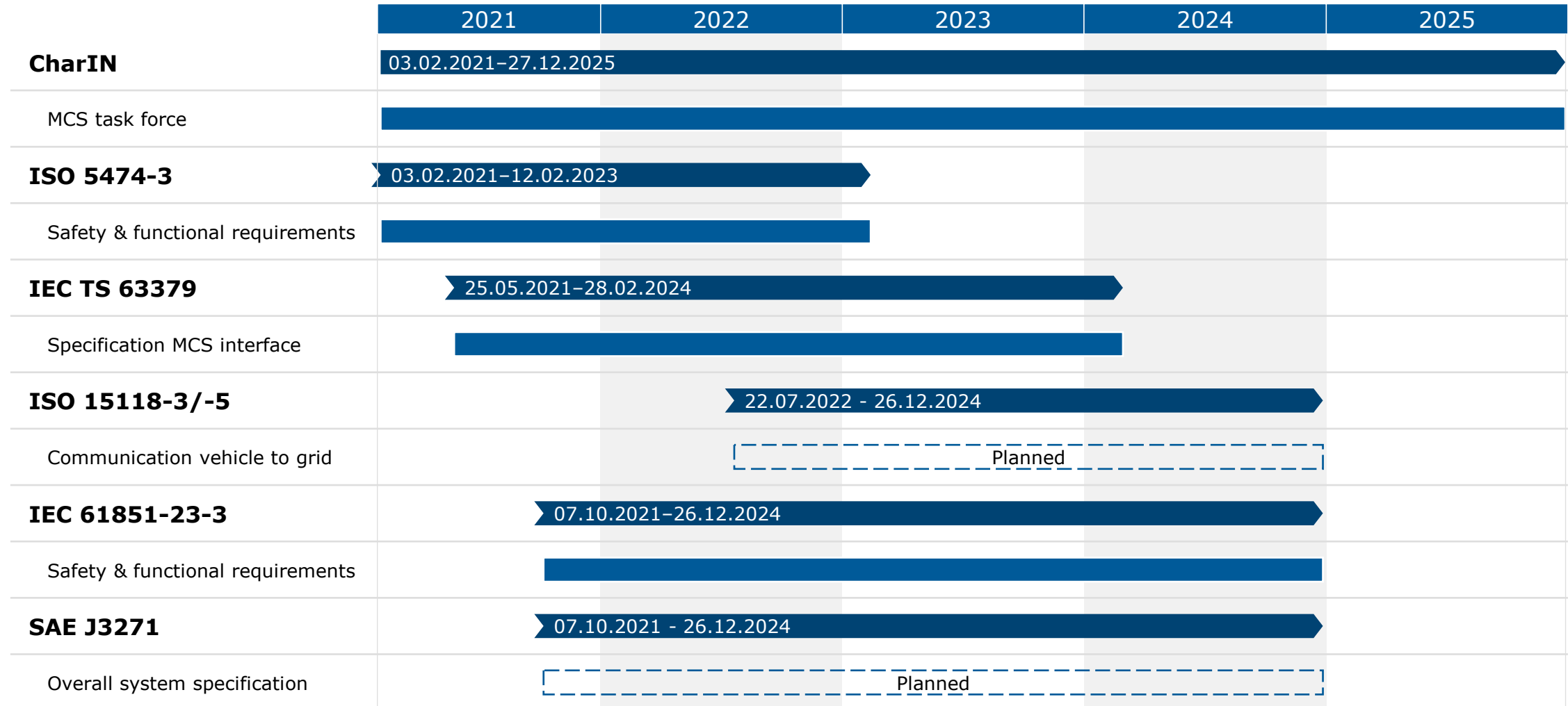




MegaWatt Chargig – A Critical Success Factor for Commercial Vehicle Electrification

Standardization

Standardization Overview

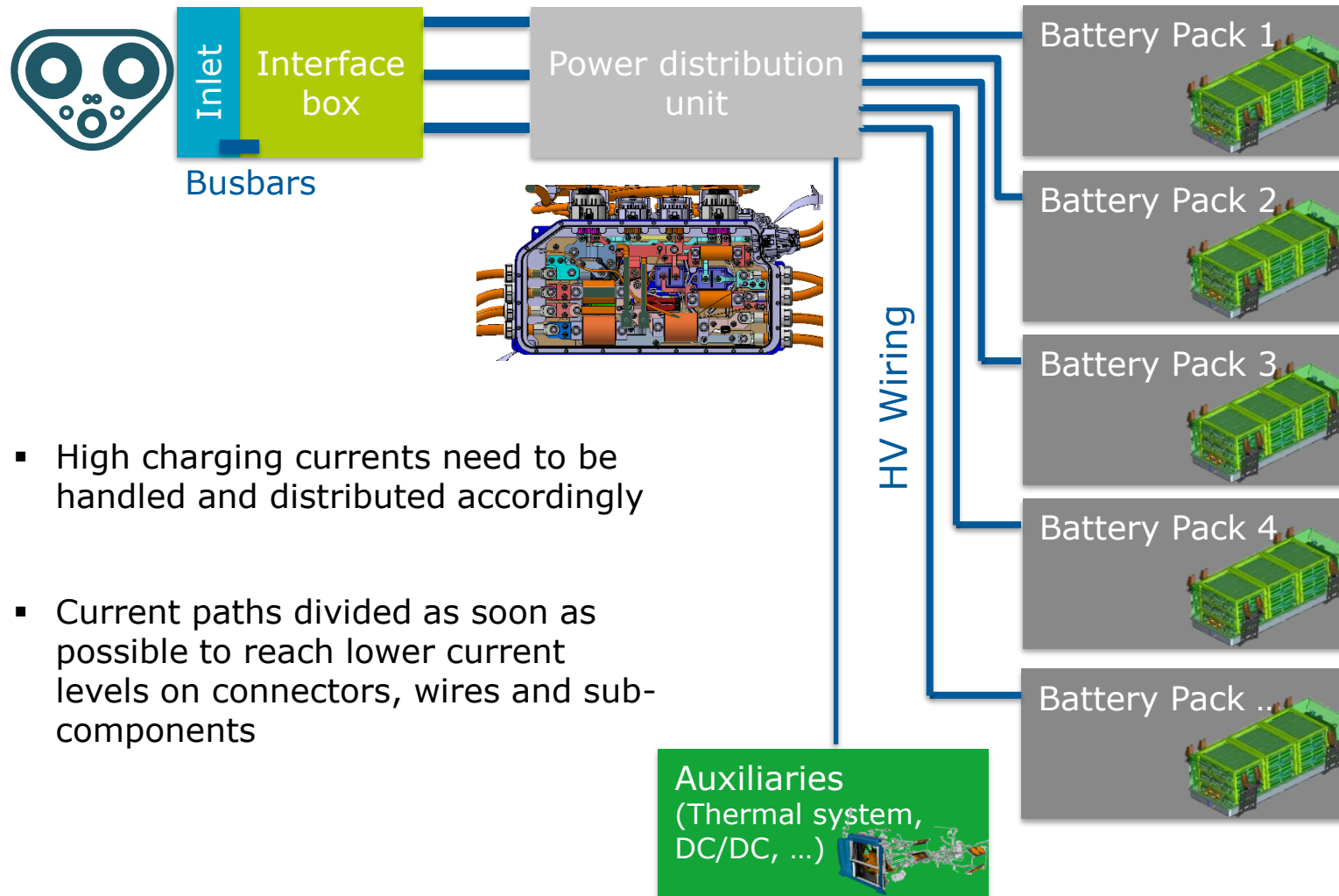


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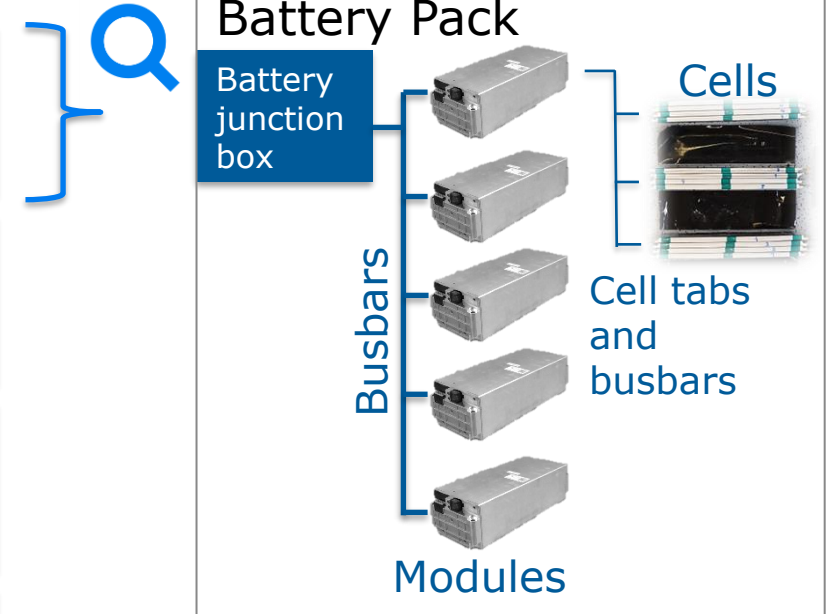
MCS System Architecture, Power Electronics & Control

Vehicle Architecture (AVL Proposal)

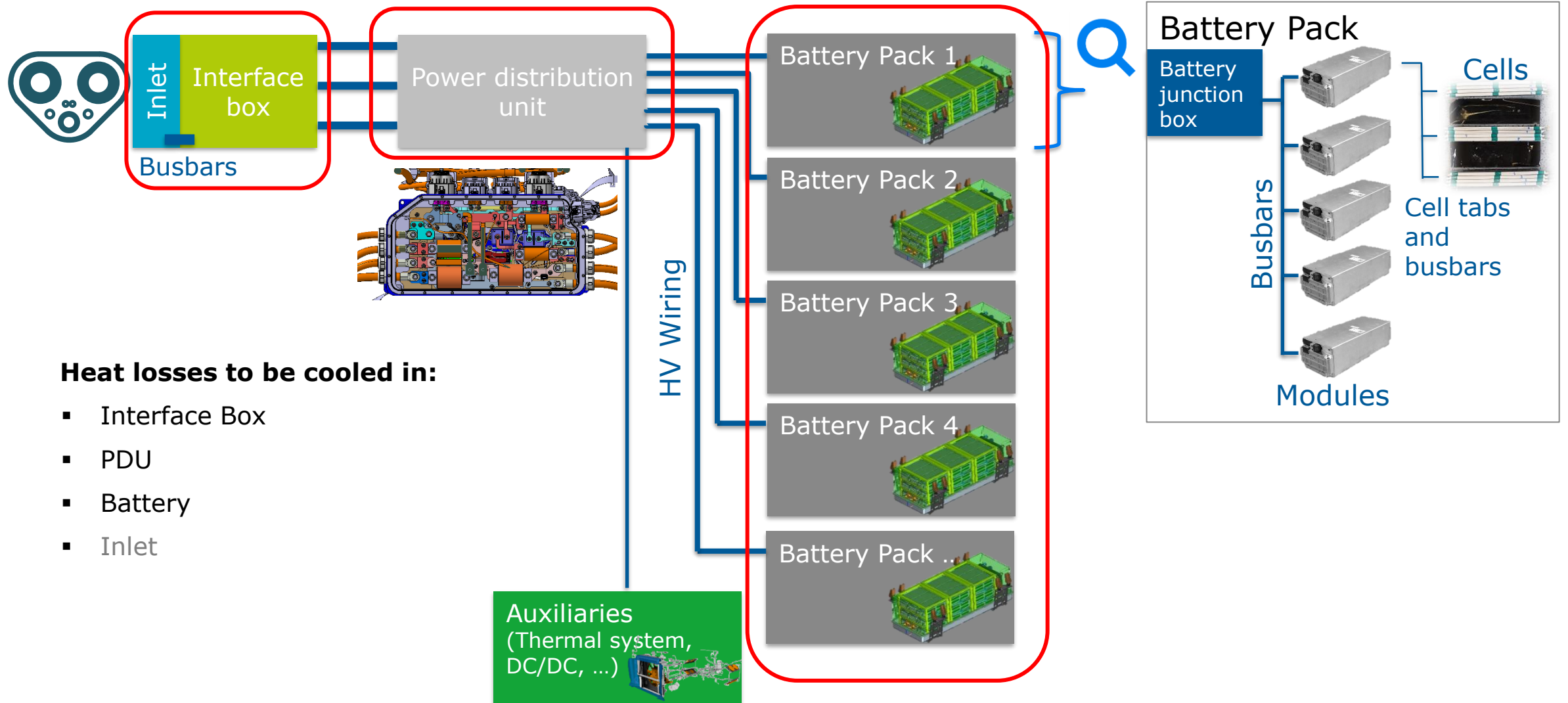
Power Distribution



- High charging currents need to be handled and distributed accordingly
- Current paths divided as soon as possible to reach lower current levels on connectors, wires and sub-components

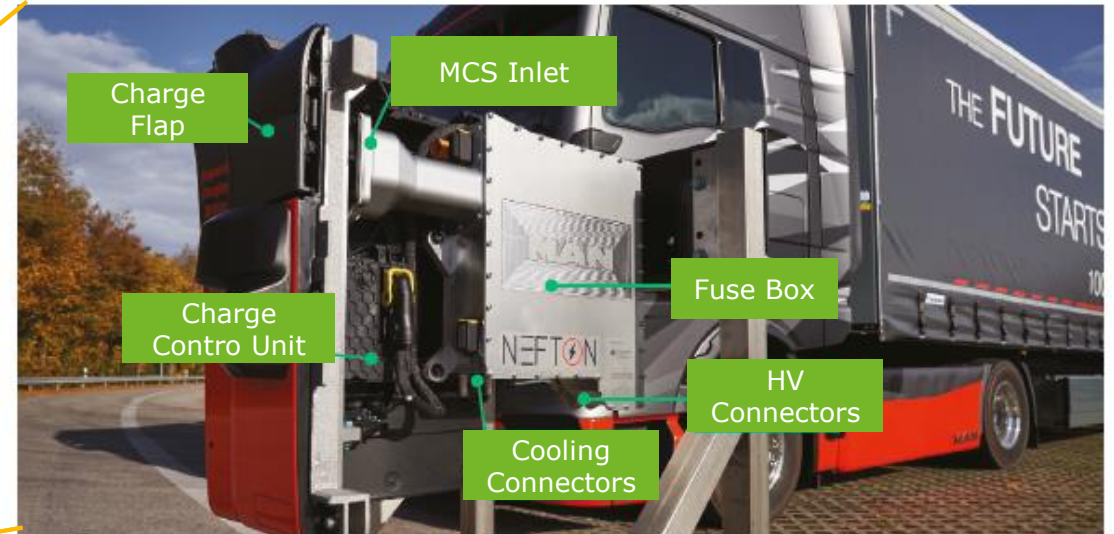
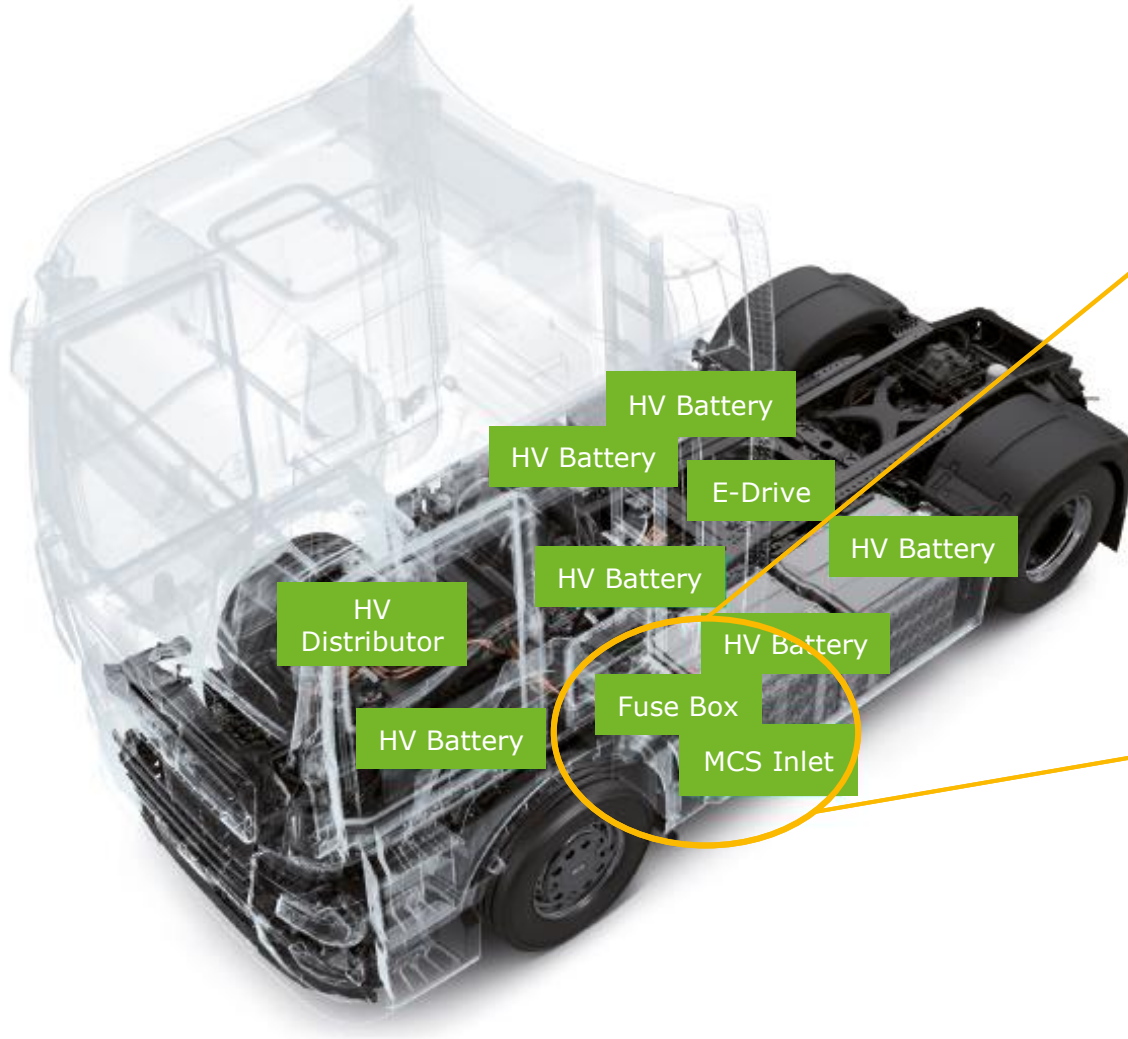


Vehicle Architecture (AVL Proposal) Cooling



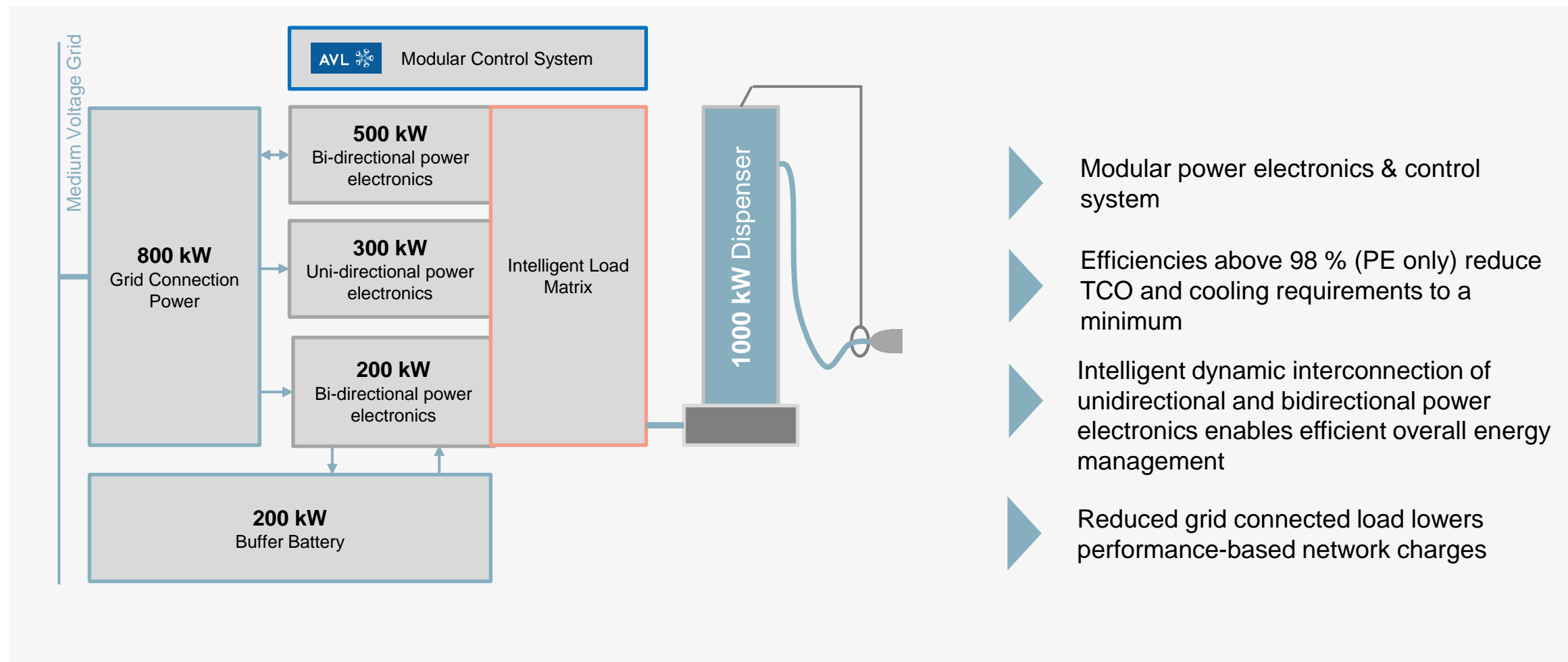
Vehicle Architecture

MAN Example from the NEFTON Project



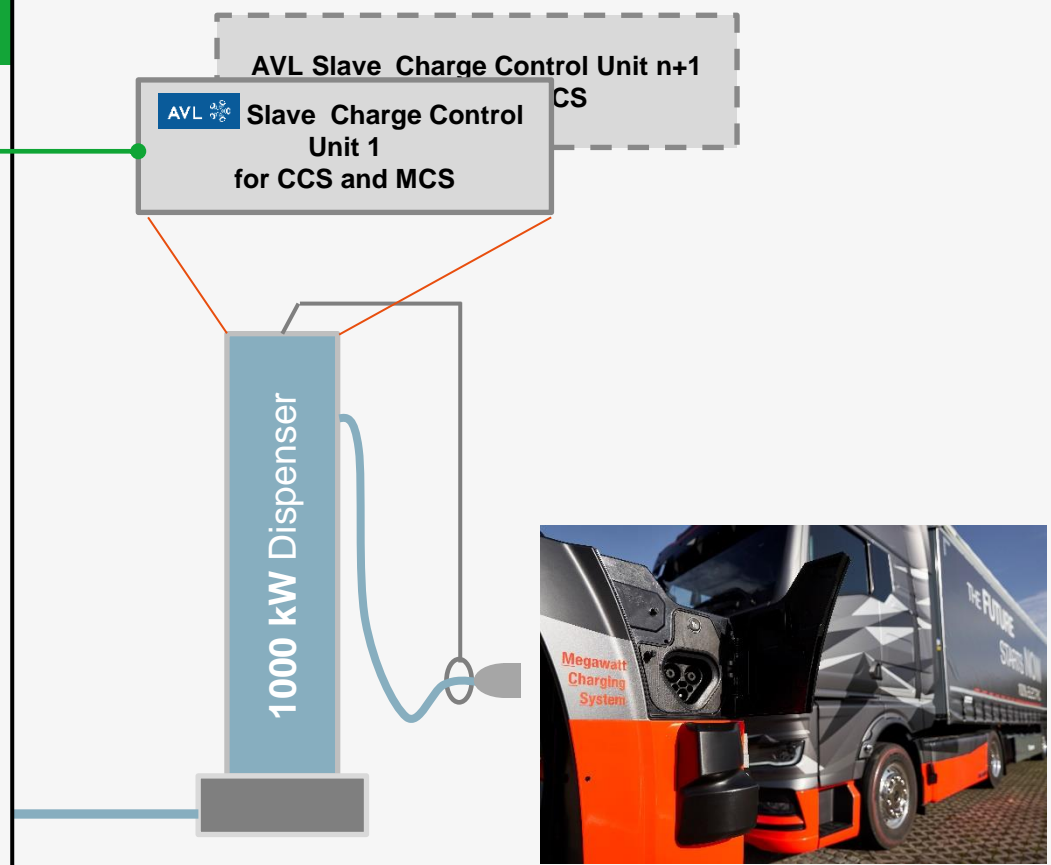
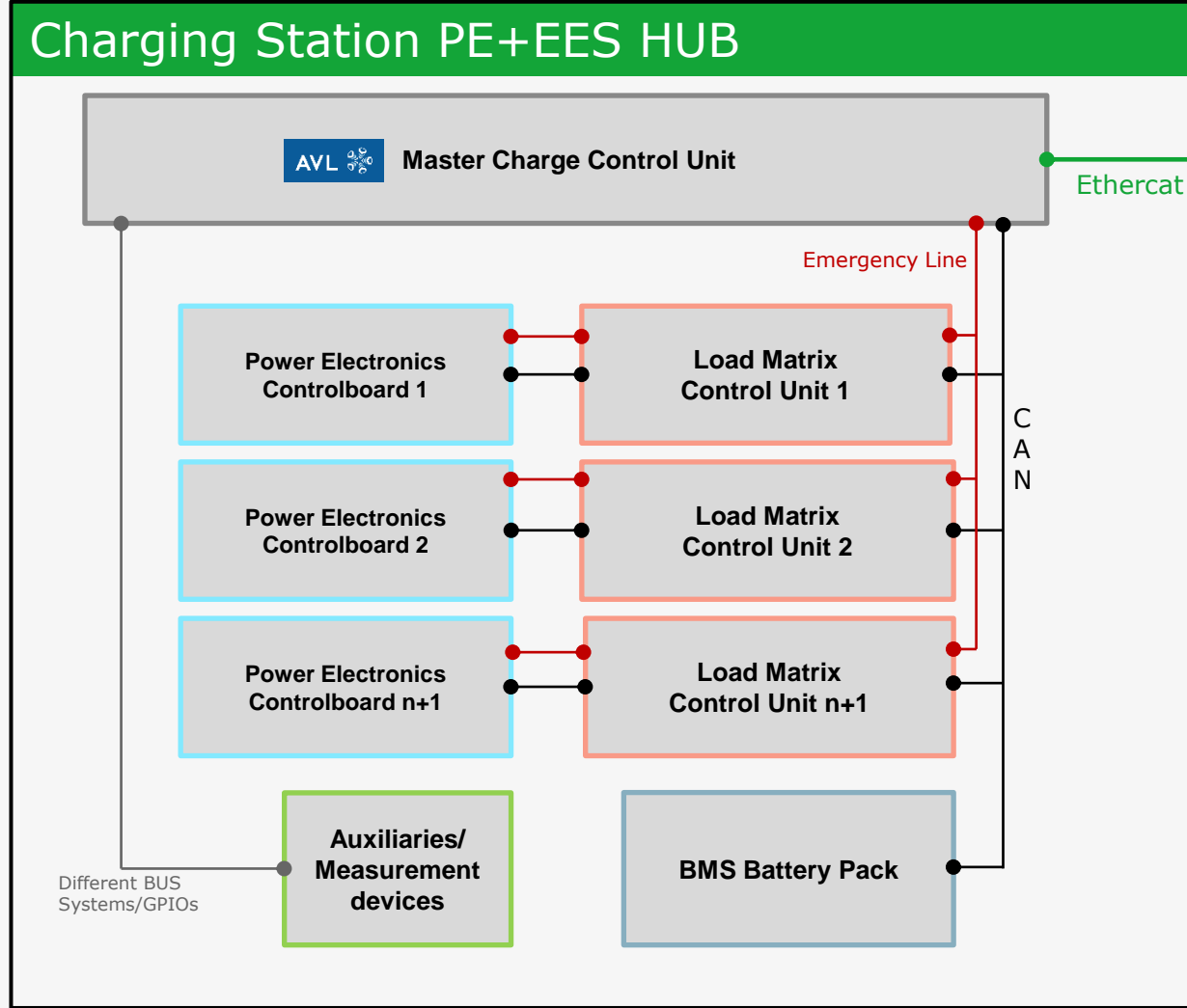
Efficient Setup of a 1 MW Charging Station

Example from the NEFTON Project



AVL's Modular Control System

Example from the NEFTON Project



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Energy Flow & Losses from Grid to Vehicle

Simulation

Description of BEV Charging Use Case

Cell Data

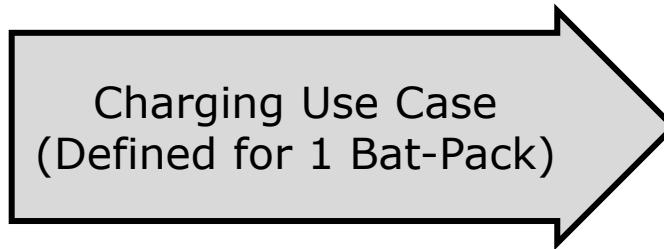
Parameter	Value
Chemistry	LFP (cost efficient cell)
Nominal Voltage	3.3 V
Capacity	27 Ah

Battery Pack data

Parameter	Value
Config	242 series / 4 parallel
Nominal Voltage	800 V
Capacity	86.2 kWh
Charging energy (20-80 %)	51,7 kWh
Charging power limit (~ 2C)	174 kW

BEV Battery System data

Parameter	Value
Number of Packs	6
Nominal Voltage	800 V
Overall Capacity	517.2 kWh (long haul truck)
Charging energy (20-80 %)	310.3 kWh
Overall charging power (2C)	~ 1000 kW

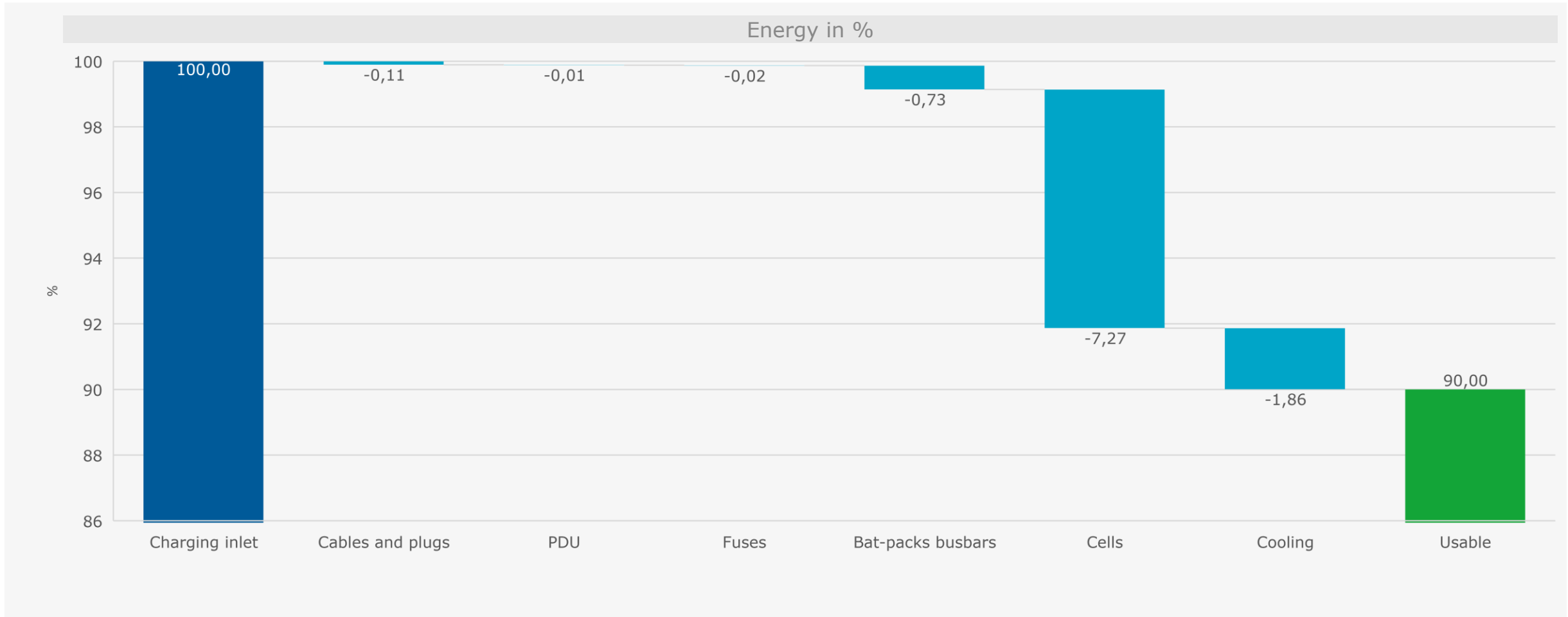


Parameter	Value
Battery Charging Power (~2C)	174 kW const
Charging energy (20→80 % SOC)	51.7 kWh

Battery Pack Charging Key Facts

Parameter	Value
Battery Charging Power (~2C)	174 kW const
Charging energy (20→80 % SOC)	51.7 kWh
Charging Time	~ 20 min
Mean Battery Terminal Voltage	865 V
Mean Battery Charging Current	201 A
Mean Cell Charging Power	161 kW
Mean Cell Charging losses	13 kW

Resulting Energy Split





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Status Funding Project NEFTON

NEFTON Project Insights

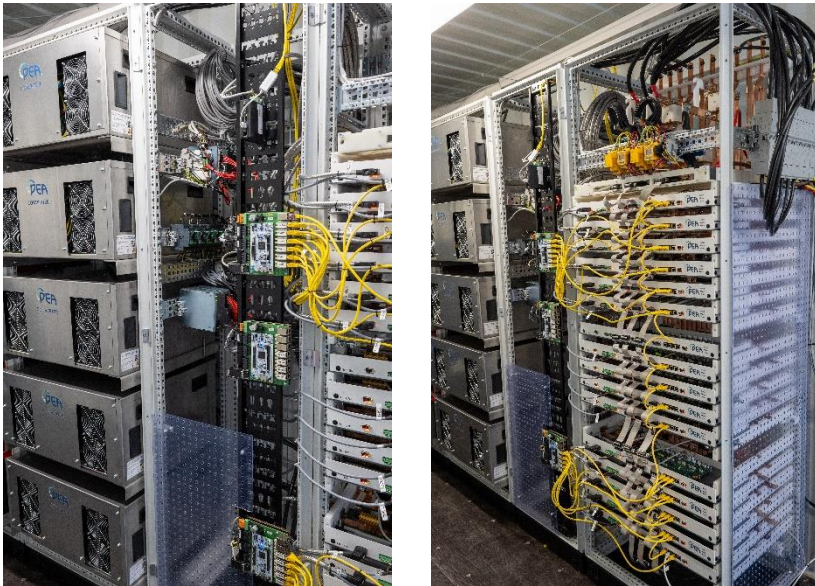
Current Status, Site: Plattling, Germany



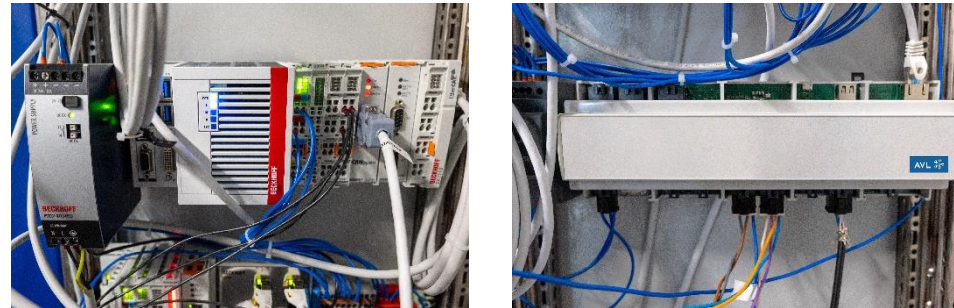
NEFTON Project Insights

Current Status, Site: Plattling, Germany

Load Matrix and Power Electronics



Modular Control System



Dispenser & Energy Storage



19th of July 2024

**Public Demonstration of
MegaWatt Charging**

Registration:

www.nefton.de

Looking forward to see you in
Plattling, Germany



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Outlook

AVL EVSE Controls

Solution for Charging Stations

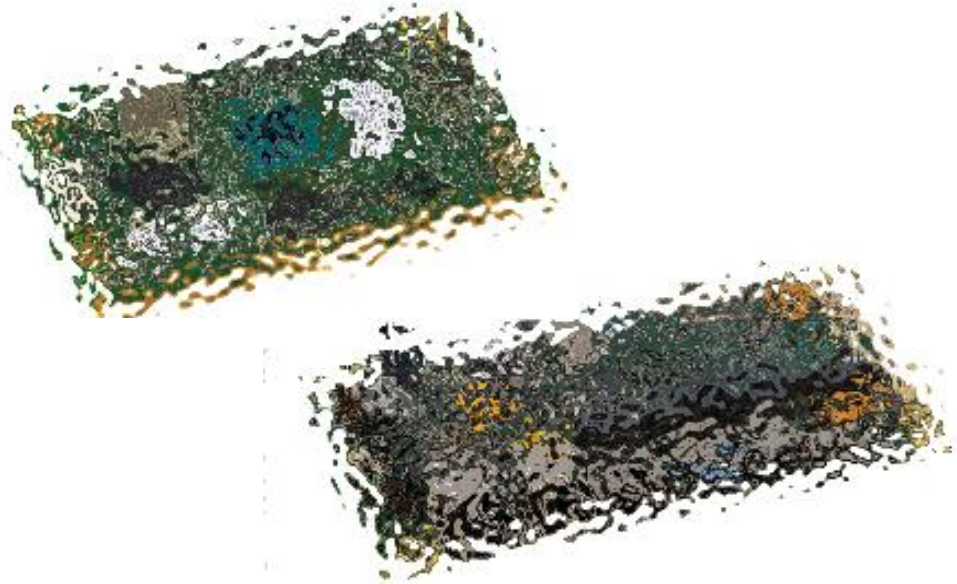
Overview - Benefits of AVL EVSE Control System:

- Modular & scalable controller concept
- Fast time to market solution
- Software for complete Charging Station Control
- Customized development on demand
 - Full access to all modules and interfaces
- All Components integrable via cap rail system
- Support of latest Charging Standards
 - CCS (ISO 15118-2 & -20 & DIN70121)
 - Chademo 0.9-2.0
 - China GB/T ready
 - MCS (preliminary version)
- Optional: White Box design data for Software and Hardware

Solution for DC Wallbox to MCS Charging Station



EVSE Controller Reference



EVSE Controller



Customized series development



Confidential

AVL contributions

System spec & design

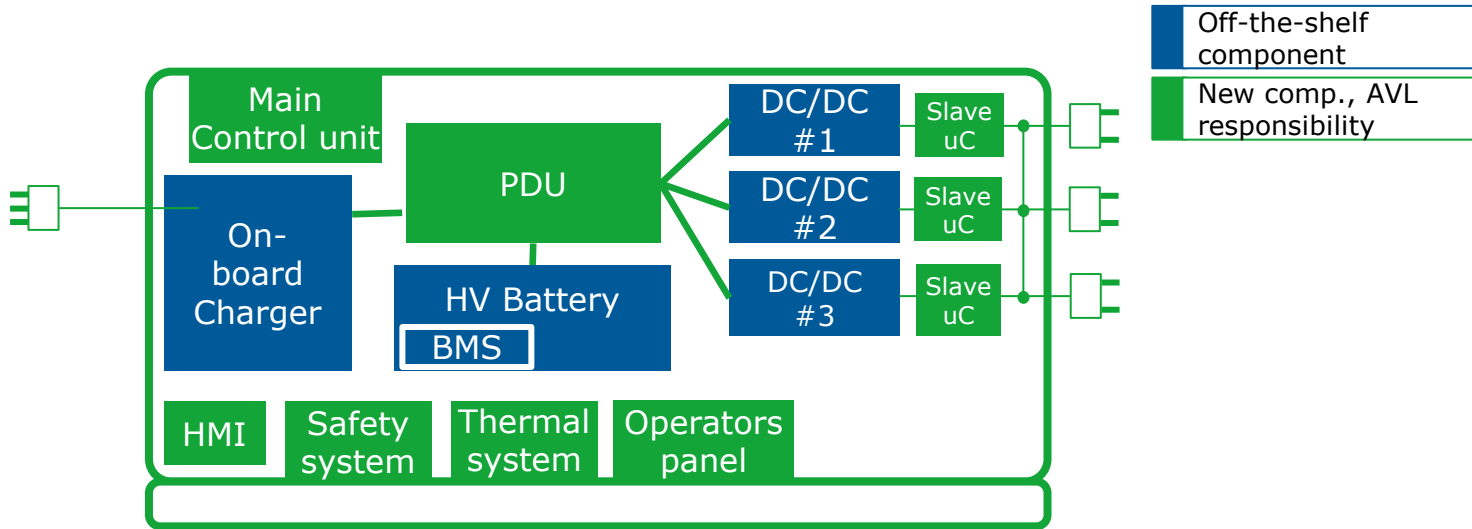
HW Design

Software Development
CCS 1/2 and Chademo

Control Unit build-up

Testing

Mobile Battery Station Reference



AVL contributions

Market Screening & Pre-Selection

System Specification & Design

Charge Control Unit & Plant Control

Charging Station Prototype Build-up

Commissioning & Testing



Charging Station



Prototype development

SOP Project Reference

EVCC Development & Validation

Requirements Engineering

Integration of VCU and EVCC functionality into on eCU

In-house HIL Testing
with Vector VT System

Charging in-field testing in Europe

Software development for CCS Standard

Safety development support

Vehicle and charging system calibration

Vehicle testing with AVL Rapid Charger

CCS SOP Software development / charging system
vehicle calibration and validation



Project

- EV C-SUV Segment
- EV Lead SOP
- VCU & EVCC Platform development
- Target: European & US Market
- Project Start: 2018
- Duration: 3 years

Specific Project Challenges

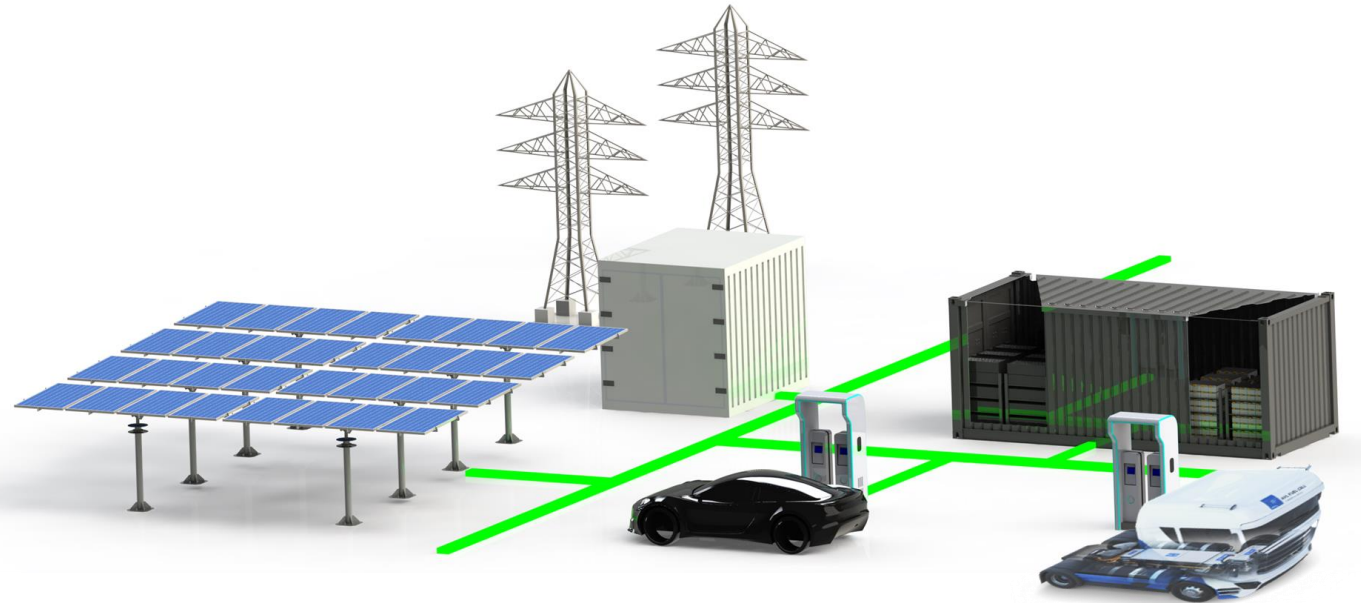
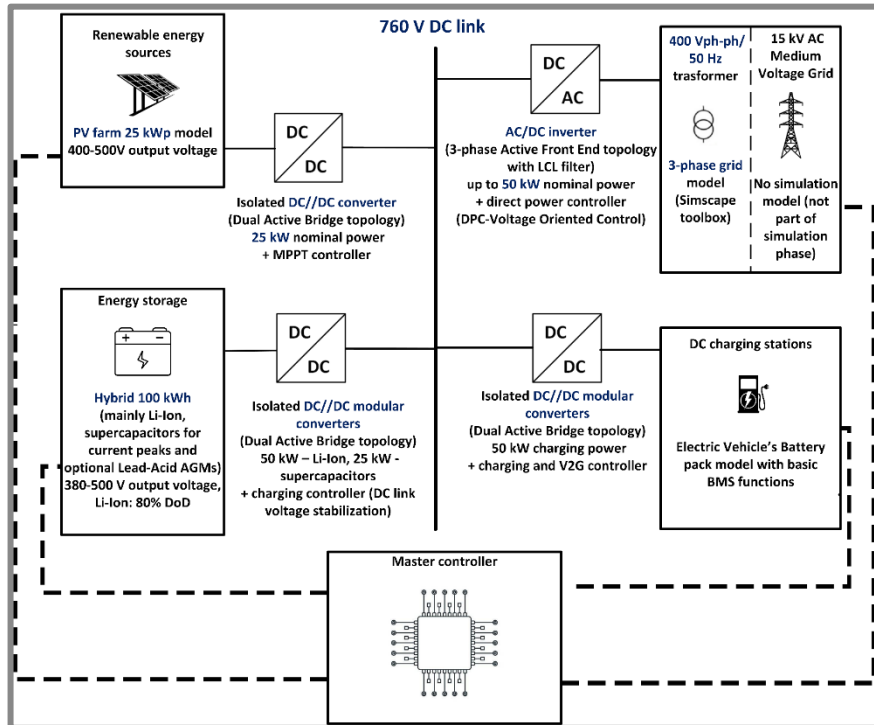
- Agile and challenging timeline
- Functional integration of EVCC into VCU
- Testing and Validation

Methods

- Agile SW development
- Dedicated Charging Validation Plan

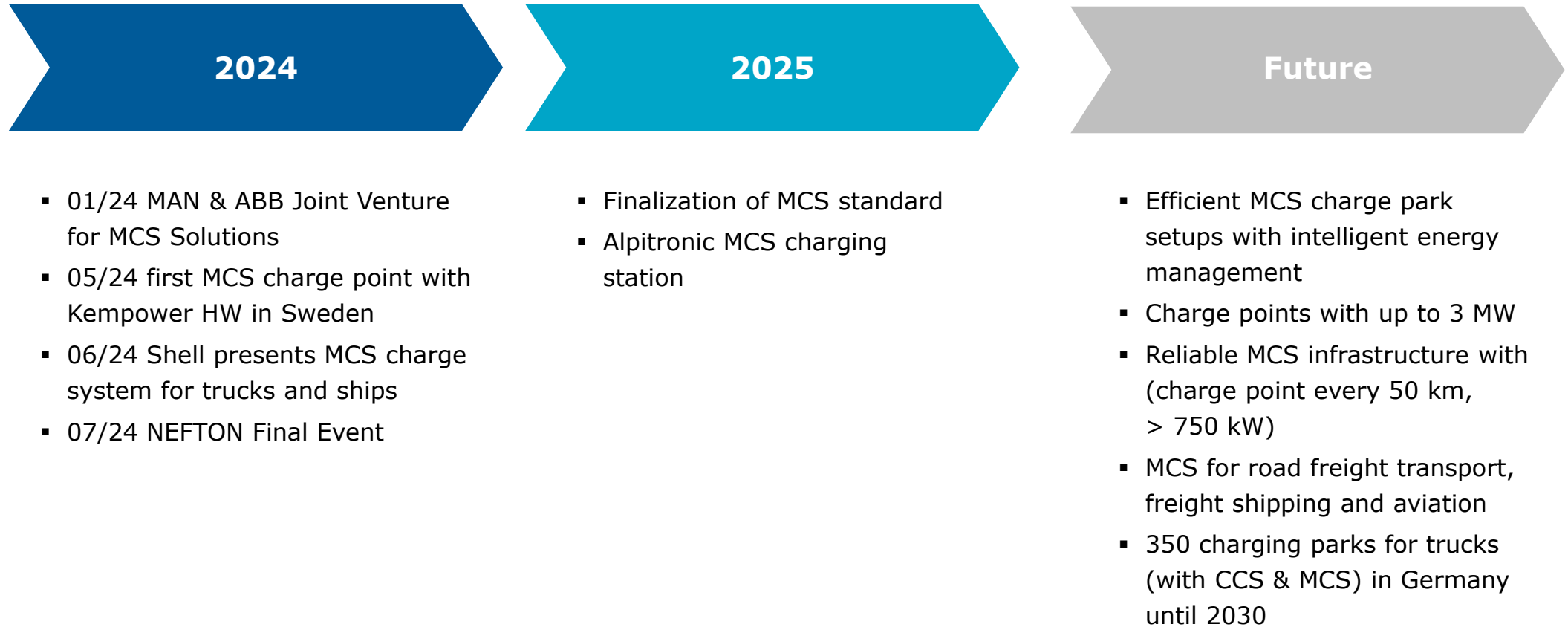
Charging Park Simulation

AVL Proven Simulation Models



- Simulation of different topologies (e. g. solid state transformer)
- Simulation of failures (e. g. load dump)
- Simulation of different power classes up to MegaWatt charging
- Simulation of different load scenarios

MCS Summary & Outlook





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Q&A

Contact



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